Polynomial time approximation of entropy of shifts of finite type

Stefan Adams, Raimundo Briceno, Brian Marcus, Ronnie Pavlov

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- Let \mathcal{A} be a finite alphabet. $\mathcal{A}^{\mathbb{Z}^d} := \{ \text{ all } d\text{-dimensional arrays of symbols from } \mathcal{A} \}.$
- Shift of finite type (SFT): Let \mathcal{F} is a *finite* list of "forbidden" patterns on *finite* sets $X = X_{\mathcal{F}} = \{x \in \mathcal{A}^{\mathbb{Z}^d} : x \text{ contains no translate of an element of } \mathcal{F}\}$
- SFT's also known as "finite memory constraints."
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- Main Example (d=2): hard square SFT $A = \{0,1\}, \mathcal{F} = \{11, \begin{array}{c} 1 \\ 1 \end{array} \}$



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- for an SFT X,

$$L_n(X) = \{ \text{ legal configurations on } B_n \}$$

Topological entropy (noiseless capacity):

$$h(X) := \lim_{n \to \infty} \frac{\log |L_n(X)|}{n^d}$$

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 A one-dimensional n.n. SFT X = X_F is a set of sequences specified by a directed graph G with vertices in A and an edge from a to b iff ab ∉ F.

Golden Mean Shift ((1, ∞) constraint): $\mathcal{F} = \{11\}$

- Adjacency matrix A of G is the square matrix indexed by A: $A_{ab} = \left\{ \begin{array}{cc} 1 & ab \notin \mathcal{F} \\ 0 & ab \in \mathcal{F} \end{array} \right\}$
- $h(X) = \log \lambda(A)$, where $\lambda(A)$ is the spectral radius of A.
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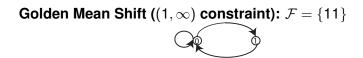
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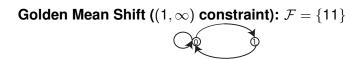


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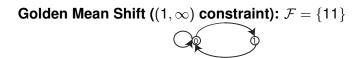
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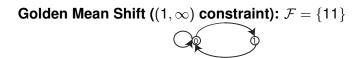
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• hard squares $A = \{0, 1\}, F = \{11, \begin{array}{c} 1 \\ 1 \end{array}\}$

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• q-checkerboard C_q : $A = \{1, ..., q\}, F = \{aa, \frac{a}{a}\}$

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$$h(C_2) = 0$$

• (Lieb):
$$h(C_3) = (3/2) \log(4/3)$$

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$$h(C_4) = ???$$

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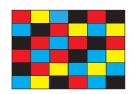
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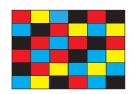
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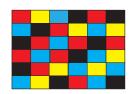
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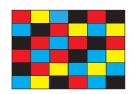


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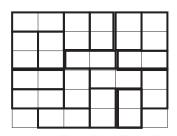
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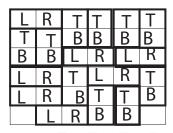




$$\mathcal{F} = \{LL, LT, LB, RR, TR, BR, \begin{array}{cccc} T & T & T & B & L & R \\ L & R & T & B & B & B \end{array} \}$$

- (Fisher-Kastelyn-Temperley): $h(\ \, \text{Dimers} \, \,) = \frac{1}{16\pi^2} \int_{-\pi}^{\pi} \int_{-\pi}^{\pi} \log(4+2\cos\theta+2\cos\phi) \, \, d\theta d\phi$
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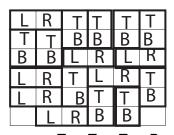




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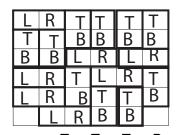
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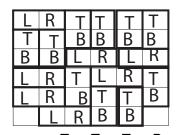
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- Exact formula known only in a few cases.
- Characterization of entropies for d ≥ 2 (Hochman-Meyerovitch):

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{right recursively enumerable (RRE) numbers h \ge 0}
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i.e, there is an algorithm that produces a sequence $r_n \ge h$ s.t. $r_n \to h$.

- Necessity: Let $r_n := \frac{\log |L_n|}{n^d}$. $r_n \to h$. Since $\lim = \inf$, each $r_n \ge h$.
- Sufficiency (hard): Emulate Turing machine with an SFT.
- RRE's can be arbitrarily poorly computable, or even non-computable.



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Given a shift-invariant Borel probability measure μ on $\mathcal{A}^{\mathbb{Z}^d}$,

• For finite $S \in \mathbb{Z}^d$,

$$H_{\mu}(S) := \sum_{x \in \mathcal{A}^S} -\mu(x) \log \mu(x) = \int -\log \mu(x) d\mu(x)$$

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$$H_{\mu}(\mathcal{S} \mid T) := \sum_{x \in \mathcal{A}^{\mathcal{S}}, y \in \mathcal{A}^{\mathcal{T}}: \; \mu(y) > 0} - \mu(x, y) \log \mu(x \mid y)$$

$$H_{\mu}(S \mid T) := \inf_{T' \in T} H_{\mu}(S \mid T')$$



Given a shift-invariant Borel probability measure μ on $\mathcal{A}^{\mathbb{Z}^d}$,

• For finite $S \subseteq \mathbb{Z}^d$,

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•
$$h(\mu) := \lim_{n \to \infty} \frac{H_{\mu}(B_n)}{n^d}$$

- d = 1: Theorem: $h(\mu) = H_{\mu}(0 \mid \{-1, -2, -3, \ldots\})$
- d = 2: Let \prec denotes lexicographic order: $(i, j) \prec (i', j')$ iff either j < j' or (j = j') and i < i'.

For $\overline{z} \in \mathbb{Z}^2$, let $\mathcal{P}(\overline{z}) := \{\overline{z}' \in \mathbb{Z}^2 : \overline{z}' \prec \overline{z}\}$ the lexicographic past of \overline{z} , and $\mathcal{P} := \mathcal{P}(0)$



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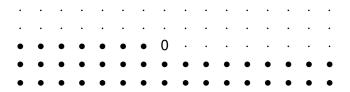


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Theorem:
$$h(\mu) = H_{\mu}(0 \mid \mathcal{P})$$
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Defn: The **information function** of μ is defined as

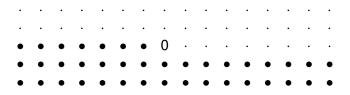
$$I_{\mu}(x) := -\log \mu(x(0)|x(\mathcal{P})) \quad (\mu - a.e.)$$

Corollary

$$h(\mu) = H_{\mu}(0|\mathcal{P}) = \int I_{\mu}(x) d\mu(x).$$



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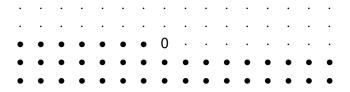
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$$h(X) = \sup_{\mu} h(\mu)$$

- Fact: The sup is always achieved. A measure which achieves the sup is called a measure of maximal entropy (MME).
- So for an MME μ , $h(X) = h(\mu) = \int I_{\mu}(x) d\mu(x)$
- Under certain conditions, $h(X) = h(\mu) = \int I_{\mu}(x) d\nu(x)$ for some other invariant measures ν
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Rough Idea for showing $h(X) = I_{u}(s^{\mathbb{Z}^{d}})$

An MME μ should be "nearly uniform". So, μ captures entropy: If $s^{\mathbb{Z}^d} \in X$. then

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bounded. Most terms are bulk terms. So, $h(X) = h(s^{2}) = 1$

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Theorem: Let X be a n.n. \mathbb{Z}^d SFT and μ an MME on X. If

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Proof of Claim, via transfer matrices

$$\mu(s^{0} \mid s^{\partial R_{n,n,n}}) = \frac{\begin{array}{c} s & s & s & s \\ s & \cdot & \cdot & \cdot & \cdot & s \\ \# & s & \cdot & \cdot & \cdot & \cdot & s \\ s & s & s & s & \cdot & \cdot & s \\ \hline s & s & s & s & s & s \\ \hline s & s & s & s & s & s \\ \hline s & \cdot & \cdot & \cdot & \cdot & s \\ \# & s & \cdot & \cdot & \cdot & \cdot & s \\ s & s & s & \cdot & \cdot & \cdot & s \\ \hline s & s & s & s & s & s \\ \hline \end{array}$$

$$= \frac{(\prod_{i=-n}^{-1} M_{i}) \hat{M}_{0}(\prod_{i=1}^{n-1} M_{i})}{(\prod_{i=-n}^{-1} M_{i}) \hat{M}_{0}(\prod_{i=1}^{n-1} M_{i})}$$

 M_i is transition matrix from column i to column i+1 compatible with $s^{\partial R_{n,n,n}}$ and

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- Weaken fixed point $s^{\mathbb{Z}^d}$ to periodic orbit
- Weaken safe symbol to topological strong spatial mixing
- Applies to
 - hard squares
 - monomer-dimers
 - q-checkerboard SFT with $q \ge 6$
- Generalize results from entropy to pressure of n n. interactions on n.n. SFT's
- Applies to large sets of temperature regions for classical models in statistical physics, in both subcritical and supercritical regions:
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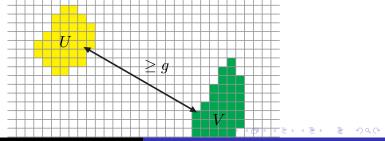
End of talk

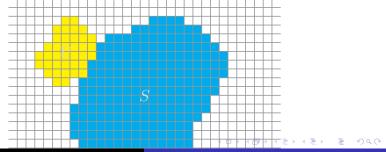
The following slides form a hodge-podge of topics that were not included in the talk.

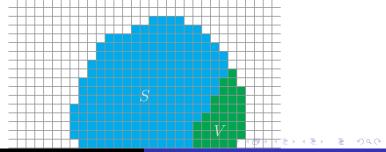
Defn of TSSM with gap *g*:

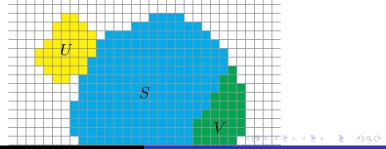
Defin of TSSM with gap g: for any disjoint $U, S, V \subseteq Z^d$ s.t. $d(U, V) \ge g$,

if $u \in A^U$, $s \in A^S$, $v \in A^V$, s.t. *us* and sv are allowed, then so is usv.









Let
$$R_{a,b,c} := [-a,-1] \times [1,c] \cup [0,b] \times [0,c]$$



- X satisfies TSSM
- ② (for d=2) For some periodic orbit O in X and all $\omega \in O$

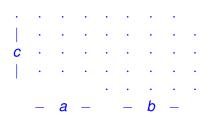
$$L(\omega) := \lim_{\substack{a,b,c \to \infty \\ c \to \infty}} \mu(\omega(0) \mid \omega(\partial R_{a,b,c}))$$
 exists

$$h(X) = -\frac{1}{|O|} \sum_{\alpha \in O} \log L(\omega)$$



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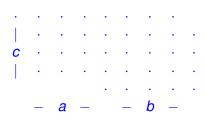
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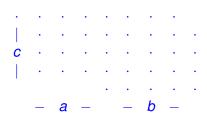
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A **Markov random field (MRF)** is a shift-invariant Borel probability measure μ on $\mathcal{A}^{\mathbb{Z}^d}$ such that for any choice of:

- $S \in \mathbb{Z}^d$,
- $T \in \mathbb{Z}^d$ s.t. $\partial S \subseteq T \subseteq \mathbb{Z}^d \setminus S$
- configuration x on S
- configuration y on T s.t. $\mu(y) > 0$,

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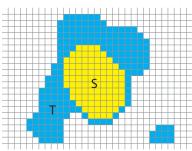
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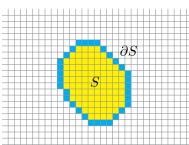
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Let *X* be a n.n. SFT. For $S \in \mathbb{Z}^d$ and $y \in \mathcal{A}^{\partial S}$, let

$$L_{\mathcal{S}}^{y}(X) := \{x \in \mathcal{A}^{\mathcal{S}} : xy \text{ is legal } \}$$

An MRF on X is **uniform** if whenever $\mu(y) > 0$, then for $x \in L_S^y(X)$

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Theorem (Lanford/Ruelle, Burton/Steif): Every MME on a n.n. SFT is a uniform MRF.



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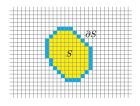
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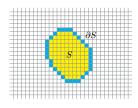
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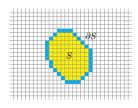
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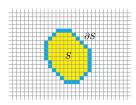
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An MRF on X is **uniform** if whenever $\mu(y) > 0$, then for $x \in L_S^y(X)$

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Theorem (Lanford/Ruelle, Burton/Steif): Every MME on a n.n. SFT is a uniform MRF.

- Since μ is an MME, μ must be a uniform MRF.
- Since s is a safe symbol,

$$\mu(\mathbf{s}^0 \mid \mathbf{s}^{\partial T}) \geq \frac{1}{|\mathcal{A}|}$$

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$$h(X) = \lim_{n \to \infty} \frac{-\log \mu(s^{B_n} \mid s^{\partial B_n})}{n^d}$$

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• By safe symbol assumption, for the remaining $\overline{z} \in B_n$,

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Theorem: Let X be a n.n. \mathbb{Z}^2 SFT and μ an MME on X. If

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$$L:=\lim_{a,b,c o\infty}\mu(s^0\mid s^{\partial R_{a,b,c}})$$
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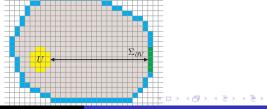
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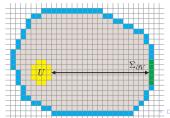
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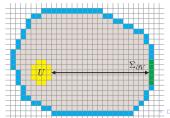
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Theorem (Briceno): Let X be a \mathbb{Z}^d n.n. SFT and μ an MME on X. If

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Applies to:

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- q-checkerboard with q ≥ 6



- Let *X* be a shift space and $f: X \to \mathbb{R}$ a continuous function.
- **Topological Pressure** (defined by Variational Principle):

$$P_X(f) := \sup_{\mu} h(\mu) + \int f d\mu$$

- Fact: The sup is always achieved.
- A measure which achieves the sup is called an equilibrium state.
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- A nearest-neighbor interaction is a shift-invariant function Φ from a set of configurations on vertices and edges in \mathbb{Z}^d to $\mathbb{R} \cup \infty$
- For a nearest-neighbor interaction Φ , the *underlying SFT*:

$$X = X_{\Phi} := \{x \in \mathcal{A}^{\mathbb{Z}^d} : \Phi(x(\{v, v'\})) \neq \infty, \text{ for all } v \sim v'\}.$$

• A nearest neighbour (n.n.) Gibbs measure μ corresponding to Φ is an MRF on X such that for $S \in \mathbb{Z}^d$, $\delta \in \mathcal{A}^{\partial S}$, $\mu(\delta) > 0$, $w \in \mathcal{A}^S$:

$$\mu(w|\delta) = \frac{e^{-U^{\Phi}(w\delta)}}{Z^{\Phi,\delta}(S)}.$$

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Examples of n.n. Gibbs measures

- uniform MME on n.n. SFT
- hard square model with activities
- ferromagnetic Ising model with no external field.

Pressure of n.n. interaction Φ:

$$P(\Phi) := \lim_{n \to \infty} \frac{\log Z^{\Phi}(B_n)}{n^d}$$

- Let $A_{\Phi}(x) := -\Phi(x(0)) \sum_{i=1}^{d} \Phi(x(0), x(e_i)).$
- Fact: $P_{X_{\Phi}}(A_{\Phi}) = P(\Phi)$.
- Lanford-Ruelle Theorem: Every equilibrium state for A_{Φ} is a Gibbs measure for Φ .
- Dobrushin Theorem: If X_{Φ} is strongly irreducible, then every Gibbs measure for Φ is an equilibrium state for A_{Φ} .
- These theorems hold in much greater generality.



Pressure of n.n. interaction Φ:

$$P(\Phi) := \lim_{n \to \infty} \frac{\log Z^{\Phi}(B_n)}{n^d}$$

- Let $A_{\Phi}(x) := -\Phi(x(0)) \sum_{i=1}^{d} \Phi(x(0), x(e_i)).$
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Theorem (Adams, Briceno, Marcus, Pavlov): Let μ a Gibbs measure for a n.n. interaction Φ with underlying \mathbb{Z}^d n.n. SFT X. If

- X satisfies TSSM
- ② For some periodic orbit O in X and all $\omega \in O$

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Then

$$P(\Phi) = \frac{1}{|O|} \sum_{\omega \in O} -\log L(\omega) + A_{\Phi}(\omega)$$



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An SFT X satisfies the **D-condition** if

- there exist sequences of finite subsets (Λ_n) , (M_n) of \mathbb{Z}^d such that $\Lambda_n \nearrow \infty$, $\Lambda_n \subseteq M_n$, $\frac{|M_n|}{|\Lambda_n|} \to 1$, such that
- for any globally admissible $v \in \mathcal{A}^{\Lambda_n}$ and finite $S \subset M_n^c$ and globally admissible $w \in \mathcal{A}^S$, we have that vw is globally admissible.

Safe symbol \Rightarrow TSSM \Rightarrow D-condition



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• Assuming adjacency matrix A is irreducible and aperiodic, there is a unique MME $\mu_{\rm max}$, which is a Markov chain given by transition matrix

$$P_{ij} = \left\{ \begin{array}{cc} \frac{r_j}{\lambda r_i} & ij \notin \mathcal{F} \\ 0 & ij \in \mathcal{F} \end{array} \right\}$$

where $\lambda = \lambda(A)$ and r is a right eigenvector for λ , and stationary vector $r_i \ell_i$ where ℓ is a left eigenvector for λ (suitably normalized)

• Thus, if $\mu(w_1 w_2 \dots w_{n-1} w_n) > 0$, then

$$\mu(w_1 w_2 \dots w_{n-1} w_n) = \frac{\ell_{w_1} r_{w_n}}{\lambda^{n-1}}$$

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Entropy representation for MME, d = 1

$$I_{\mu}(x) = -\log \mu(x(0)| x(\mathcal{P}))$$

= -\log P_{x_0 x_{-1}}
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• So, for *all* invariant measures ν ,

$$\int I_{\mu}(x)d\nu(x) = \int (\log \lambda + \log r_{x_{-1}} - \log r_{x_0})d\nu(x)
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In particular, if the SFT has a fixed point $x^* := a^{\mathbb{Z}}$ and ν is the delta measure on x^* , then on

$$h(X) = \int I_{\mu}(x) d\nu(x) = I_{\mu}(x^*) = -\log \mu(x^*)$$

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