

Randomized Coordinate Descent with Arbitrary Sampling: Algorithms and Complexity

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based on joint work with Peter Richtarik and Dominique
Cisba(University of Edinburgh)

- First-order methods for composite convex optimization
- Randomized coordinate descent method
- Adaptive sampling
- Expected separable overapproximation

Problem and Motivation

Problem Setup

$$\min_{x \in \mathbb{R}^n} [F(x) := f(x) + \psi(x)]$$

- $f : \mathbb{R}^n \rightarrow \mathbb{R}$ is convex and smooth:

$$f(x+h) \leq f(x) + \langle \nabla f(x), h \rangle + \frac{1}{2} \|Ah\|^2, \quad \forall x, h \in \mathbb{R}^n$$

- $\psi : \mathbb{R}^n \rightarrow \mathbb{R} \cup \{+\infty\}$ is proper, convex, closed and separable:

$$\psi(x) \equiv \sum_{i=1}^n \psi^i(x^i)$$

Motivation: Empirical Risk Minimization

ERM:

$$\min_{w \in \mathbb{R}^d} \left[P(w) \stackrel{\text{def}}{=} \frac{1}{n} \sum_{i=1}^n \phi_i(A_i^\top w) + \lambda g(w) \right]$$

- supervised learning/image processing...;
- train a linear predictor $w \in \mathbb{R}^d$;
- n training samples $A_1, \dots, A_n \in \mathbb{R}^d$;

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- train a linear predictor $w \in \mathbb{R}^d$;
- n training samples $A_1, \dots, A_n \in \mathbb{R}^d$;
- convex loss function $\phi_i : \mathbb{R} \rightarrow \mathbb{R}$;
 - ex.: Squared loss ($\phi_i(a) = \frac{1}{2}(a - b_i)^2$), Logistic loss ($\phi_i(a) = \log(1 + e^a)$), ...

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 - ex.: Squared loss ($\phi_i(a) = \frac{1}{2}(a - b_i)^2$), Logistic loss ($\phi_i(a) = \log(1 + e^a)$), ...
- convex regularizer $g : \mathbb{R}^d \rightarrow \mathbb{R} \cup \{+\infty\}$;
 - ex.: L_1 regularization ($g(w) = \|w\|_1$), L_2 regularization ($g(w) = \frac{1}{2}\|w\|_2^2$), ...

Primal Dual Formulation

- ERM:

$$\min_{w \in \mathbb{R}^d} \left[P(w) \stackrel{\text{def}}{=} \frac{1}{n} \sum_{i=1}^n \phi_i(A_i^\top w) + \lambda g(w) \right]$$

- Dual problem of ERM:

$$\max_{\alpha \in \mathbb{R}^n} D(\alpha) \stackrel{\text{def}}{=} \underbrace{-\lambda g^* \left(\frac{1}{\lambda n} \sum_{i=1}^n A_i \alpha_i \right)}_{\substack{\text{smooth if} \\ g \text{ strongly convex}}} - \underbrace{\frac{1}{n} \sum_{i=1}^n \phi_i^*(-\alpha_i)}_{\substack{\text{convex} \\ \text{and separable}}}$$

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- Optimality conditions:

$$\mathbf{OPT1} : w^* = \nabla g^* \left(\frac{1}{\lambda n} A \alpha^* \right)$$

$$\mathbf{OPT2} : \alpha_i^* = -\nabla \phi_i(A_i^\top w^*), \quad \forall i = 1, \dots, n.$$

First-order methods for non-strongly convex composite optimization

Problem Setup

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Proximal Gradient

- 1: **Parameters:** vector $v \in \mathbb{R}_{++}^n$
 - 2: **Initialization:** choose $x_0 \in \text{dom } \psi$
 - 3: **for** $k \geq 0$ **do**
 - 4: **for** $i \in [n]$ **do**
 - 5: $x_{k+1}^i = \arg \min_{x \in \mathbb{R}} \left\{ \langle \nabla_i f(x_k), x \rangle + \frac{v_i}{2} \|x - x_k^i\|_i^2 + \psi^i(x) \right\}$
 - 6: **end for**
 - 7: **end for**
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- proximal operator of ψ^i is easily computable.

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- proximal operator of ψ^i is easily computable.
 - a.k.a. explicite-implicite/forward-backward method \subset splitting algorithm [Lions & Mercier 79], [Eckstein & Bertsekas 89]

Accelerated Proximal Gradient

- 1: **Parameters:** vector $v \in \mathbb{R}_{++}^n$
- 2: **Initialization:** choose $x_0 \in \text{dom}(\psi)$, set $z_0 = x_0$ and $\theta_0 = 1$
- 3: **for** $k \geq 0$ **do**
- 4: **for** $i \in [n]$ **do**
- 5: $z_{k+1}^i = \arg \min_{z \in \mathbb{R}} \{ \langle \nabla_i f((1 - \theta_k)x_k + \theta_k z_k), z \rangle + \frac{\theta_k v_i}{2} \|z - z_k^i\|_i^2 + \psi^i(z) \}$
- 6: **end for**
- 7: $x_{k+1} = (1 - \theta_k)x_k + \theta_k z_{k+1}$
- 8: $\theta_{k+1} = \frac{\sqrt{\theta_k^4 + 4\theta_k^2} - \theta_k^2}{2}$
- 9: **end for**

[Nesterov 83, 04], [Beck & Teboulle 08](FISTA), [Tseng 08],

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Convergence Analysis

Theorem

If $v_i = L$ for any $i \in [n]$ with $L \geq \lambda_{\max}(A^T A)$, then the iterates $\{x_k\}$ of the proximal gradient method satisfy:

$$F(x_k) - F(x_*) \leq \frac{L \|x_0 - x_*\|^2}{2k}, \quad \forall k \geq 1.$$

Theorem (Tseng 08)

If $v_i = L$ for any $i \in [n]$ with $L \geq \lambda_{\max}(A^T A)$, then the iterates $\{x_k\}_k$ of the accelerated proximal gradient algorithm satisfy:

$$F(x_k) - F(x_*) \leq \frac{2L \|x_0 - x_*\|^2}{(k+1)^2}, \quad \forall k \geq 1.$$

Randomized Coordinate Descent

Randomized coordinate descent

- 1: **Parameters:** vector $v \in \mathbb{R}_{++}^n$
 - 2: **Initialization:** choose $x_0 \in \text{dom } \psi$
 - 3: **for** $k \geq 0$ **do**
 - 4: Generate random $i \in [n]$ uniformly
 - 5: $x_{k+1} \leftarrow x_k$
 - 6: $x_{k+1}^i = \arg \min_{x \in \mathbb{R}} \left\{ \langle \nabla_i f(x_k), x \rangle + \frac{v_i}{2} \|x - x_k^i\|_i^2 + \psi^i(x) \right\}$
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- $v = \text{Diag}(A^\top A)$ [Nesterov 10], [Shalev-Shwartz & Tewari 11], [Richtarik & Takac 11]

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- $v = \text{Diag}(A^T A)$ [Nesterov 10], [Shalev-Shwartz & Tewari 11], [Richtarik & Takac 11]
- Other variants [Wright 15]
 - Cyclic (Gauss-Seidel) [Canutescu & Dunbrack 03]
 - Greedy [Wu & Lange 08] [Nutini et. al 15]

Parallel Randomized Coordinate Descent

Parallel coordinate descent

- 1: **Parameters:** $\tau \in [n]$, vector $v \in \mathbb{R}_{++}^n$
 - 2: **Initialization:** choose $x_0 \in \text{dom } \psi$
 - 3: **for** $k \geq 0$ **do**
 - 4: Generate a random subset $S_k \subset [n]$ of size τ uniformly
 - 5: $x_{k+1} \leftarrow x_k$
 - 6: **for** $i \in S_k$ **do**
 - 7:
$$x_{k+1}^i = \arg \min_{x \in \mathbb{R}} \left\{ \langle \nabla_i f(x_k), x \rangle + \frac{v_i}{2} \|x - x_k^i\|^2 + \psi^i(x) \right\}$$
 - 8: **end for**
 - 9: **end for**
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 - 8: **end for**
 - 9: **end for**
-

$$v = \left(1 + \frac{(\tau-1)(\omega-1)}{\max(n-1, 1)} \right) \text{Diag}(A^T A) \quad [\text{Richtarik \& Takac 13}]$$

where ω is the maximal number of nonzero elements in each row of A .

Convergence Analysis

Theorem (Richtarik & Takac 13)

Define the level-set distance

$$\mathcal{R}_v(x_0, x_*) \stackrel{\text{def}}{=} \max_x \{ \|x - x_*\|_v^2 : F(x) \leq F(x_0) \}.$$

Under the assumption

$$\mathcal{R}_v(x_0, x_*) < +\infty,$$

we have:

$$\begin{aligned} & \mathbb{E}[F(x_k)] - F(x_*) \\ & \leq \frac{2n \max\{\mathcal{R}_v(x_0, x_*), F(x_0) - F(x_*)\}}{2n \max\{\mathcal{R}_v(x_0, x_*) / (F(x_k) - F(x_*)), 1\} + \tau k} \end{aligned}$$

Accelerated Parallel Proximal Coordinate Descent

- 1: **Parameters:** $\tau \in [n]$, vector $v \in \mathbb{R}_{++}^n$
- 2: **Initialization:** choose $x_0 \in \text{dom}(\psi)$, set $z_0 = x_0$ and $\theta_0 = \tau/n$
- 3: **for** $k \geq 0$ **do**
- 4: $y_k = (1 - \theta_k)x_k + \theta_k z_k$
- 5: Generate a random subset $S_k \subset [n]$ of size τ uniformly
- 6: $z_{k+1} \leftarrow z_k$
- 7: **for** $i \in S_k$ **do**
- 8:
$$z_{k+1}^i = \arg \min_{z \in \mathbb{R}} \left\{ \langle \nabla_i f(y_k), z \rangle + \frac{\theta_k v_i n}{2\tau} \|z - z_k^i\|_i^2 + \psi^i(z) \right\}$$
- 9: **end for**
- 10: $x_{k+1} = y_k + \theta_k n/\tau \cdot (z_{k+1} - z_k)$
- 11:
$$\theta_{k+1} = \frac{\sqrt{\theta_k^4 + 4\theta_k^2} - \theta_k}{2}$$
- 12: **end for**

[Nesterov 10], [Lee & Sidford 13], [Fercoq & Richtarik 13]...

Convergence Analysis

Theorem (Fercoq & Richtarik 13)

Choose

$$v_i = \sum_{j=1}^m \left(1 + \frac{(\tau - 1)(\omega_j - 1)}{\max(n - 1, 1)} \right) A_{ji}^2, \quad i = 1, 2, \dots, n.$$

The iterates $\{x_k\}$ of APPROX for all $k \geq 1$ satisfies:

$$\begin{aligned} & \mathbb{E}[F(x_k) - F(x_*)] \\ & \leq \frac{4 \left[\left(1 - \frac{\tau}{n}\right) (F(x_0) - F(x_*)) + \frac{1}{2} \|x_0 - x_*\|_v^2 \right]}{((k - 1)\tau/n + 2)^2}. \end{aligned}$$

Summary

Parallel Coordinate Descent
(choose subset of size τ uniformly)

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$$\tau = 1$$

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Coordinate Descent

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Accelerated Parallel Proximal Coordinate Descent
(choose subset of size τ uniformly)

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(choose subset of size τ uniformly)

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Accelerated Proximal
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(choose subset of size τ uniformly)

$$\tau = n$$

Accelerated Proximal
Gradient

Randomized coordinate descent method with arbitrary sampling

Q. and Richtarik. Coordinate descent with arbitrary sampling I:
algorithms and complexity, *Optimization methods and software*, 2016.

Sampling

- Sampling is a set-valued random variable:

$$\hat{S} \subset \{1, \dots, n\}$$

- Probability vector:

$$p_i = \mathbb{P}(i \in \hat{S}), \quad i \in \{1, \dots, n\}$$

- Proper sampling:

$$p_i = \mathbb{P}(i \in \hat{S}) > 0, \quad \forall i \in \{1, \dots, n\}$$

- Serial sampling:

$$\mathbb{P}(|\hat{S}| = 1) = 1$$

- Uniform sampling:

$$p_1 = \dots = p_n = \frac{\mathbb{E}[|\hat{S}|]}{n}$$

Algorithm

- 1: **Parameters:** proper sampling \hat{S} with probability vector $p = (p_1, \dots, p_n) \in [0, 1]^n$, $v \in \mathbb{R}_{++}^n$, sequence $\{\theta_k\}_{k \geq 0} \subset (0, 1]$
- 2: **Initialization:** choose $x_0 \in \text{dom } \psi$ and set $z_0 = x_0$
- 3: **for** $k \geq 0$ **do**
- 4: $y_k = (1 - \theta_k)x_k + \theta_k z_k$
- 5: Generate a random set of blocks $S_k \sim \hat{S}$
- 6: $z_{k+1} \leftarrow z_k$
- 7: **for** $i \in S_k$ **do**
- 8: $z_{k+1}^i = \arg \min_{z \in \mathbb{R}} \left\{ \langle \nabla_i f(y_k), z \rangle + \frac{\theta_k v_i}{2p_i} \|z - z_k^i\|_i^2 + \psi^i(z) \right\}$
- 9: **end for**
- 10: $x_{k+1} = y_k + \theta_k p^{-1} \cdot (z_{k+1} - z_k)$
- 11: **end for**

Efficient Implementation

- 1: **Parameters:** proper sampling \hat{S} with probability vector $p = (p_1, \dots, p_n)$, $v \in \mathbb{R}_{++}^n$, sequence $\{\theta_k\}_{k \geq 0}$
- 2: **Initialization:** choose $x^0 \in \text{dom } \psi$, set $z^0 = x^0$, $u^0 = 0$ and $\alpha_0 = 1$
- 3: **for** $k \geq 0$ **do**
- 4: Generate a random set of coordinates $S_k \sim \hat{S}$
- 5: $z^{k+1} \leftarrow z^k$, $u^{k+1} \leftarrow u^k$
- 6: **for** $i \in S_k$ **do**
- 7: $\Delta z_i^k = \arg \min_{t \in \mathbb{R}} \left\{ t \nabla_i f(\alpha_k u^k + z^k) + \frac{\theta_k v_i}{2 p_i} |t|^2 + \psi_i(z_i^k + t) \right\}$
- 8: $z_i^{k+1} \leftarrow z_i^k + \Delta z_i^k$
- 9: $u_i^{k+1} \leftarrow u_i^k - \alpha_k^{-1} (1 - \theta_k p_i^{-1}) \Delta z_i^k$
- 10: $\alpha_{k+1} = (1 - \theta_{k+1}) \alpha_k$
- 11: **end for**
- 12: **end for**
- 13: **OUTPUT:** $x^{k+1} = z^k + \alpha_k u^k + \theta_k p^{-1} (z^{k+1} - z^k)$

Convergence Analysis

Lemma

Let \hat{S} be an arbitrary proper sampling and $v \in \mathbb{R}_{++}^n$ be such that

$$\mathbb{E}[f(x + h_{[\hat{S}]})] \leq f(x) + \langle \nabla f(x), h \rangle_p + \frac{1}{2} \|h\|_{v \circ p}^2, \quad \forall x, h \in \mathbb{R}^n.$$

Let $\{\theta_k\}_{k \geq 0}$ be arbitrary sequence of positive numbers in $(0, 1]$. Then for the sequence of iterates produced by the algorithm and all $k \geq 0$, the following recursion holds:

$$\begin{aligned} & \mathbb{E}_k \left[\hat{F}_{k+1} + \frac{\theta_k^2}{2} \|z^{k+1} - x^*\|_{v \circ p}^2 \right] \\ & \leq \left[\hat{F}_k + \frac{\theta_k^2}{2} \|z^k - x^*\|_{v \circ p}^2 \right] - \theta_k (\hat{F}_k - F^*). \end{aligned}$$

Convergence Analysis

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Let \hat{S} be an arbitrary proper sampling and $v \in \mathbb{R}_{++}^n$ be such that

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Let $\{\theta_k\}_{k \geq 0}$ be arbitrary sequence of positive numbers in $(0, 1]$. Then for the sequence of iterates produced by the algorithm and all $k \geq 0$, the following recursion holds:

$$\begin{aligned} & \mathbb{E}_k \left[\hat{F}_{k+1} + \frac{\theta_k^2}{2} \|z^{k+1} - x^*\|_{v \circ p}^2 \right] \\ & \leq \left[\hat{F}_k + \frac{\theta_k^2}{2} \|z^k - x^*\|_{v \circ p}^2 \right] - \theta_k (\hat{F}_k - F^*). \end{aligned}$$

$\hat{F}_k \geq F(x_k)$ if $\psi \equiv 0$ or $\theta_k \leq \min p_i$

Convergence Results

$$(f, \hat{S}) \sim ESO(v) + \begin{cases} \psi \equiv 0 & \text{or} \\ \theta_k \leq \min p_i \end{cases}$$

- $\theta_k = \theta_0$

$$\mathbb{E} \left[F \left(\frac{x^k + \theta_0 \sum_{t=1}^{k-1} x^t}{1 + (k-1)\theta_0} \right) \right] - F^* \leq \frac{C}{(k-1)\theta_0 + 1}$$

- $\theta_{k+1} = \frac{\sqrt{\theta_k^4 + 4\theta_k^2 - \theta_k^2}}{2}$

$$\mathbb{E}[F(x^k)] - F^* \leq \frac{4C}{((k-1)\theta_0 + 2)^2}$$

where

$$C = (1 - \theta_0)(F(x^0) - F^*) + \frac{\theta_0^2}{2} \|x^0 - x^*\|_{v \circ p^{-2}}^2$$

Corollaries-Parallel Coordinate Descent

Corollary

The iterates $\{x_k\}$ of Parallel Coordinate Descent satisfy:

$$\begin{aligned} & \mathbb{E}[F(x_k)] - F(x_*) \\ & \leq \frac{n}{(k-1)\tau + n} \left[\left(1 - \frac{\tau}{n}\right) (F(x_0) - F(x_*)) + \frac{1}{2} \|x_0 - x_*\|_v^2 \right] \end{aligned}$$

Compare with

- [Richtarik & Takac 13]:

$$\max_x \{ \|x - x_*\|_v^2 : F(x) \leq F(x_0) \} < +\infty$$

- [Lu & Xiao 14] ($\tau = 1$):

$$\mathbb{E}[F(x_k)] - F(x_*) \leq \frac{n}{n+k} \left[(F(x_0) - F(x_*)) + \frac{1}{2} \|x_0 - x_*\|_v^2 \right]$$

Corollaries-Smooth Minimization

Corollary

If $\psi \equiv 0$, then the iterates $\{x_k\}$ of accelerated coordinate descent satisfy:

$$\mathbb{E} [f(x^k)] - f^* \leq \frac{2\|x^0 - x^*\|_{\text{vop}}^2}{(k+1)^2}, \quad k \geq 1.$$

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Corollary

If $\psi \equiv 0$, then the iterates $\{x_k\}$ of accelerated coordinate descent satisfy:

$$\mathbb{E} [f(x^k)] - f^* \leq \frac{2\|x^0 - x^*\|_{\text{vop}^{-2}}^2}{(k+1)^2}, \quad k \geq 1.$$

Define $L_i = A_i^\top A_i$ for $i = 1, \dots, n$.

Corollary

If each step we update coordinate i with probability

$$p_i \sim \sqrt{L_i},$$

then $\mathbb{E} [f(x^k)] - f^* \leq \frac{2(\sum_i \sqrt{L_i})^2 \|x^0 - x^*\|^2}{(k+1)^2}, \quad k \geq 1.$

Corollaries-Smooth Minimization

Serial sampling \hat{S} , $v = L$:

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The probability minimizing the right-hand side is:

$$p_i^* = \frac{(L_i \|x_i^* - x_i^0\|^2)^{\frac{1}{3}}}{\sum_{j=1}^n (L_j \|x_j^* - x_j^0\|^2)^{\frac{1}{3}}}, \quad i = 1, \dots, n.$$

Stochastic dual coordinate ascent with adaptive sampling

Cisba, Q. and Richtarik. Stochastic dual coordinate ascent with adaptive sampling, *International Conference on Machine Learning, 2015*.

Primal Dual Formulation

- ERM:

$$\min_{w \in \mathbb{R}^d} \left[P(w) \stackrel{\text{def}}{=} \frac{1}{n} \sum_{i=1}^n \phi_i(A_i^\top w) + \lambda g(w) \right]$$

- Dual problem of ERM:

$$\max_{\alpha \in \mathbb{R}^n} D(\alpha) \stackrel{\text{def}}{=} \underbrace{-\lambda g^* \left(\frac{1}{\lambda n} \sum_{i=1}^n A_i \alpha_i \right)}_{\text{smooth}} - \underbrace{\frac{1}{n} \sum_{i=1}^n \phi_i^*(-\alpha_i)}_{\gamma\text{-strongly convex and separable}}$$

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$$\mathbf{OPT1} : w^* = \nabla g^* \left(\frac{1}{\lambda n} A \alpha^* \right)$$

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Stochastic Dual Coordinate Ascent

Primal solution

For $t \geq 0$:

1. $w^t = \nabla g^*(\frac{1}{\lambda n} A \alpha^t)$

Dual solution

For $t \geq 0$:

1. $\alpha^{t+1} = \alpha^t$;

2. **Randomly pick $i_t \in \{1, \dots, n\}$;**

3. Update $\alpha_{i_t}^{t+1}$:

$$\alpha_{i_t}^{t+1} = \arg \max_{\beta \in \mathbb{R}} \left\{ -\phi_{i_t}^*(-\beta) - (A_{i_t}^\top w^t) \beta - \frac{\|A_{i_t}\|^2}{2\lambda n} |\beta - \alpha_{i_t}^t|^2 \right\}$$

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Uniform and Importance Sampling

Uniform sampling (SDCA: [Shalev-Shwartz & Zhang 13],...)

$$p_i = \mathbf{Prob}(i_t = i) \sim \frac{1}{n},$$

Iteration complexity:

$$\tilde{O} \left(n + \frac{\max_i \|A_i\|^2}{\lambda\gamma} \right)$$

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Importance sampling (Iprox-SDCA: [Zhan & Zhang 15'],...)

$$p_i = \mathbf{Prob}(i_t = i) \sim \|A_i\|^2 + \lambda\gamma n,$$

Iteration complexity:

$$\tilde{O} \left(n + \frac{\frac{1}{n} \sum_{i=1}^n \|A_i\|^2}{\lambda\gamma} \right)$$

Adaptive Sampling

- Each dual variable has a natural measure of progress:

$$\kappa_i^t \stackrel{\text{def}}{=} \alpha_i^t + \nabla \phi_i(A_i^\top w^t), \quad i = 1, \dots, n$$

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- A sampling distribution p is coherent with κ^t if for all $i \in [n]$:

$$\kappa_i^t \neq 0 \Rightarrow p_i > 0.$$

Stochastic Dual Coordinate Ascent

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For $t \geq 0$:

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Adaptive Stochastic Dual Coordinate Ascent

Primal solution

For $t \geq 0$:

1. $w^t = \nabla g^*(\frac{1}{\lambda n} A \alpha^t)$

Dual solution

For $t \geq 0$:

1. $\alpha^{t+1} = \alpha^t$;
2. **Randomly pick $i_t \in \{1, \dots, n\}$ according to a distribution p^t coherent with dual residue κ^t ;**

3. Update $\alpha_{i_t}^{t+1}$:

$$\alpha_{i_t}^{t+1} = \arg \max_{\beta \in \mathbb{R}} \left\{ -\phi_{i_t}^*(-\beta) - (A_{i_t}^\top w^t) \beta - \frac{\|A_{i_t}\|^2}{2\lambda n} |\beta - \alpha_{i_t}^t|^2 \right\}$$

Convergence Theorem

Theorem (AdaSDCA)

Consider AdaSDCA. If at each iteration $t \geq 0$,

$$\theta(\kappa^t, p^t) \stackrel{\text{def}}{=} \frac{n\lambda\gamma \sum_i |\kappa_i^t|^2}{\sum_{i:\kappa_i^t \neq 0} (p_i^t)^{-1} (\|A_i\|^2 + n\lambda\gamma) |\kappa_i^t|^2} \leq \min_{i:\kappa_i^t \neq 0} p_i^t,$$

then

$$\mathbb{E}[P(w^t) - D(\alpha^t)] \leq \frac{1}{\tilde{\theta}_t} \prod_{k=0}^t (1 - \tilde{\theta}_k) (D(\alpha^*) - D(\alpha^0)),$$

for all $t \geq 0$ where

$$\tilde{\theta}_t \stackrel{\text{def}}{=} \frac{\mathbb{E}[\theta(\kappa^t, p^t)(P(w^t) - D(\alpha^t))]}{\mathbb{E}[P(w^t) - D(\alpha^t)]}.$$

Optimal Adaptive Sampling Probability

$$\begin{aligned} p^*(\kappa^t) = & \arg \max \theta(\kappa^t, p) \\ \text{s.t.} \quad & p \in \mathbb{R}_+^n, \sum_i p_i = 1 \\ & p \text{ is coherent with } \kappa^t \\ & \theta(\kappa^t, p) \leq \min_{i:\kappa_i^t \neq 0} p_i \end{aligned}$$

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$$\begin{aligned} \tilde{p}^*(\kappa^t) = & \arg \max \theta(\kappa^t, p) \\ \text{s.t.} \quad & p \in \mathbb{R}_+^n, \sum_{i=1}^n p_i = 1 \end{aligned}$$

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$$\begin{aligned} \mathbf{p}^*(\kappa^t) = \arg \max \quad & \theta(\kappa^t, \mathbf{p}) \\ \text{s.t.} \quad & \mathbf{p} \in \mathbb{R}_+^n, \quad \sum_i p_i = 1 \\ & \mathbf{p} \text{ is coherent with } \kappa^t \\ & \theta(\kappa^t, \mathbf{p}) \leq \min_{i:\kappa_i^t \neq 0} p_i \end{aligned}$$

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$$(\tilde{\mathbf{p}}^*(\kappa^t))_i \sim |\kappa_i^t| \sqrt{\|A_i\|^2 + n\lambda\gamma}, \quad \forall i \in [n].$$

Exact Relaxation for Squared Loss

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Exact Relaxation for Squared Loss

Theorem (AdaSDCA for squared loss)

Consider AdaSDCA. If all the loss functions $\{\phi_i\}$ are *squared loss functions*, then

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Optimal adaptive sampling probability is given by:

$$(\tilde{p}^*(\kappa^t))_i \sim |\kappa_i^t| \sqrt{\|A_i\|^2 + n\lambda\gamma}, \quad \forall i \in [n].$$

Dual solution

For $t \geq 1$:

1. Compute **dual residue** κ^t : $\kappa_i^t = \alpha_i^t + \nabla \phi_i(A_i^\top w^t)$
Set $p_i^t \sim |\kappa_i^t| \sqrt{\|A_i\|^2 + n\lambda\gamma}$
2. Randomly pick $i_t \in \{1, \dots, n\}$ with probability proportional to p^t
3. Update $\alpha_{i_t}^t$
$$\alpha_{i_t}^t = \arg \max_{\beta \in \mathbb{R}} \left\{ -\phi_{i_t}^*(\beta) - (A_{i_t}^\top w^{t-1})\beta - \frac{\|A_{i_t}\|^2}{2\lambda n} |\beta - \alpha_{i_t}^{t-1}|^2 \right\}$$

Heuristic and Efficient Variant of AdaSDCA

AdaSDCA+:

Dual solution

For $t \geq 1$:

1. If $\text{mod}(t, n) = 0$, then

Option I: Adaptive Sampling Probability

Compute dual residue κ^t : $\kappa_i^t = \alpha_i^t + \nabla \phi_i(A_i^\top w^t)$

Set $p_i^t \sim |\kappa_i^t| \sqrt{\|A_i\|^2 + n\lambda\gamma}$

Option II: Importance Sampling Probability

Set $p_i^t \sim \|A_i\|^2 + n\lambda\gamma$

2. Randomly pick $i_t \in \{1, \dots, n\}$ according to p^t
3. Update $\alpha_{i_t}^t$
4. Update Probability: $p^{t+1} \sim (p_1^t, \dots, p_{i_t}^t/m, \dots, p_n^t)$

Computational Cost per Epoch

ALGORITHM	COST OF AN EPOCH
SDCA	$O(\text{nnz})$
Iprox-SDCA	$O(\text{nnz} + n \log(n))$
ADASDCA	$O(n \cdot \text{nnz})$
ADASDCA+	$O(\text{nnz} + n \log(n))$

Table 1: One epoch computational cost of different algorithms

Numerical Experiments

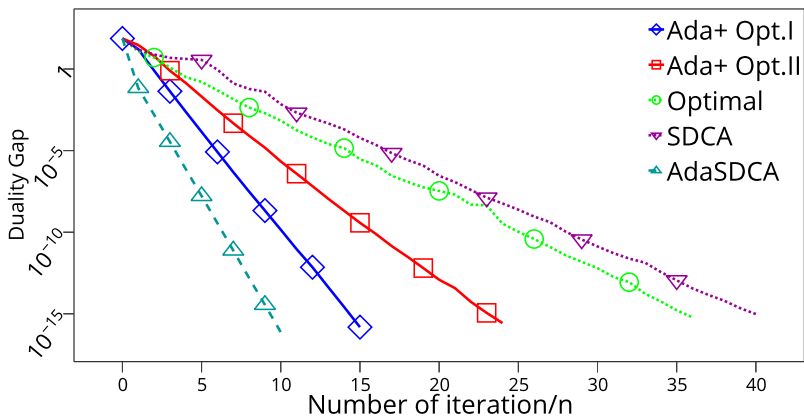


Figure 1: **w8a** dataset $d = 300$, $n = 49749$, Quadratic loss with L_2 regularizer, $\lambda = 1/n$, $\gamma = 1$.

Numerical Experiments

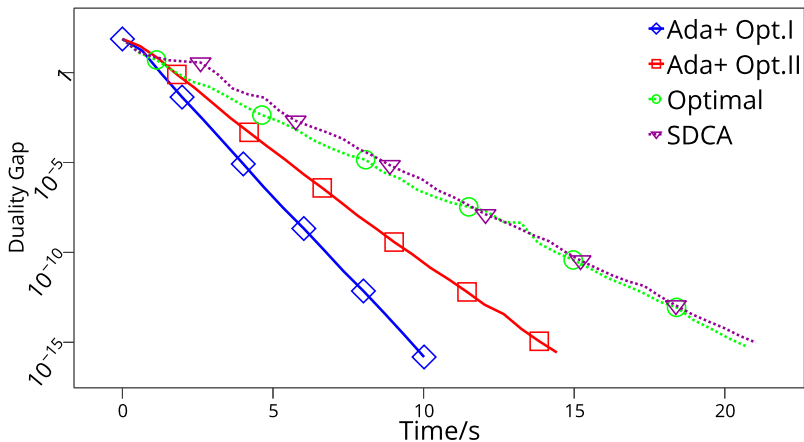


Figure 2: **w8a** dataset $d = 300$, $n = 49749$, Quadratic loss with L_2 regularizer, $\lambda = 1/n$, $\gamma = 1$.

Numerical Experiments

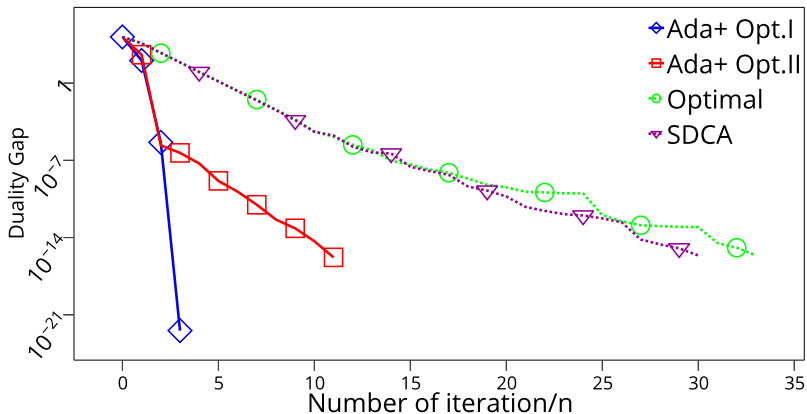


Figure 3: **cov1** dataset: $d = 54, n = 581,012$. Smooth Hinge loss with L_2 regularizer, $\lambda = 1/n, \gamma = 1$.

Numerical Experiments

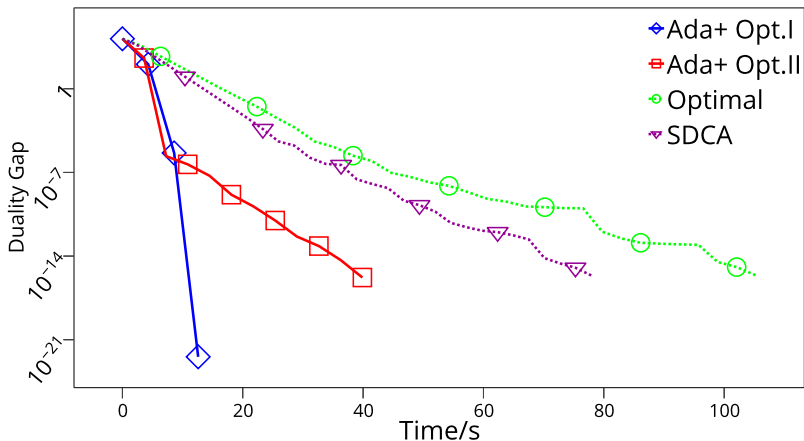


Figure 4: **cov1** dataset: $d = 54$, $n = 581,012$. Smooth Hinge loss with L_2 regularizer, $\lambda = 1/n$, $\gamma = 1$.

Numerical Experiments

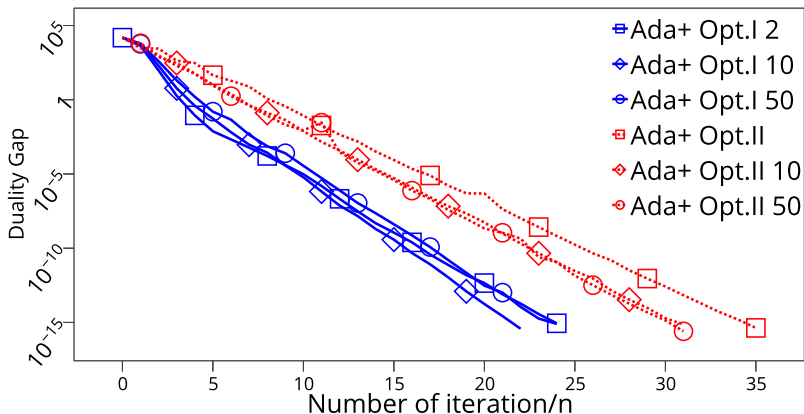


Figure 5: **cov1** dataset: $d = 54, n = 581,012$. Smooth Hinge loss with L_2 regularizer, $\lambda = 1/n, \gamma = 1$. comparison of different choices of the constant m .

More on ESO

Q. and Richtarik. Coordinate descent with arbitrary sampling II: expected separable overapproximation, *Optimization methods and software*, 2016.

- The function f admits an expected separable overapproximation (ESO) w.r.t. \hat{S} and $v \in \mathbb{R}_+^n$, denoted as $(f, \hat{S}) \sim ESO(v)$, if

$$\mathbb{E}[f(x + h_{[\hat{S}]})] \leq f(x) + \langle \nabla f(x), h \rangle_p + \frac{1}{2} \|h\|_{v \circ p}^2, \quad \forall x, h \in \mathbb{R}^n.$$

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- Recall the smoothness assumption:

$$f(x + h) \leq f(x) + \langle \nabla f(x), h \rangle + \frac{1}{2} \|Ah\|^2, \quad \forall x, h \in \mathbb{R}^n$$

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$$\mathbb{E}[\|Ah_{[\hat{S}]}\|^2] = h^\top \mathbb{E}[l_{\hat{S}}^\top A^\top A l_{\hat{S}}] h \leq \|h\|_{vop}^2, \quad \forall h \in \mathbb{R}^n$$

Deriving Stepsize

Find $v \in \mathbb{R}_+^n$ such that

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then

$$P \circ (A^\top A) = \sum_{j=1}^m P \circ (A_j^\top A_j) = \sum_{j=1}^m P_{[J_j]} \circ (A_j^\top A_j)$$

Deriving Stepsize

Theorem (ESO with coupling between sampling and data)

Let \hat{S} be an arbitrary sampling and $v = (v_1, \dots, v_n)$ be defined by:

$$v_i = \sum_{j=1}^m \lambda'(J_j \cap \hat{S}) A_{ji}^2, \quad i = 1, 2, \dots, n,$$

where

$$\lambda'(J \cap \hat{S}) := \max_{h \in \mathbb{R}^n} \{h^T P_{[J]} h : h^T \text{Diag}(\mathbb{P}_{[J]}) h \leq 1\}.$$

Then $(f, \hat{S}) \sim \text{ESO}(v)$.

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Tight bounds for:

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$$\lambda'(J \cap \hat{S}) = 1 + \frac{(|J| - 1)(\tau - 1)}{\max(n - 1, 1)} .$$

Deriving Stepsize

Tight bounds for:

- serial sampling $\lambda'(J \cap \hat{S}) = 1$;
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$$\lambda'(J \cap \hat{S}) = 1 + \frac{(|J| - 1)(\tau - 1)}{\max(n - 1, 1)} .$$

- distributed sampling with datas equally partitionned on c processors, each of which draws independently a τ -nice sampling ([Fercoq, Q. , Richtarik & Takac 14])

$$\lambda'(J \cap \hat{S}) \leq \left(1 + \frac{1}{\tau - 1}\right) \left(1 + \frac{(|J| - 1)(\tau - 1)}{\max(n/c - 1, 1)}\right) .$$

Conclusion

- Unified convergence analysis for Randomized coordinate descent method
 - Accelerated Randomized coordinate descent method
 - Arbitrary sampling
- Convergence condition (ESO)+Formulae for computing admissible stepsizes
- Adaptive sampling using duality gap