# Polynomial time approximation of entropy of shifts of finite type 

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## $\mathbb{Z}^{d}$ Shifts of finite type

- Let $\mathcal{A}$ be a finite alphabet.
$\mathcal{A}^{\mathbb{Z}^{d}}:=\{$ all $d$-dimensional arrays of symbols from $\mathcal{A}\}$.
- Shift of finite type (SFT):

Let $\mathcal{F}$ is a finite list of "forbidden" patterns on finite sets, $X=X_{\mathcal{F}}=$
$\left\{x \in \mathcal{A}^{\mathbb{Z}^{d}}: x\right.$ contains no translate of an element of $\left.\mathcal{F}\right\}$

- SFT's also known as "finite memory constraints."
- Nearest neighbor (n.n.) SFT: an SFT where all forbidden patterns are patterns on edges of $\mathbb{Z}^{d}$
- Main Example $(d=2)$ : hard square SFT


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## Topological entropy

- d-dimensional cube: $B_{n}:=[0, n-1]^{d}$
- for an SFT $X$, $L_{n}(X)=\left\{\right.$ legal configurations on $\left.B_{n}\right\}$
- Topological entropy (noiseless capacity):

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- A one-dimensional n.n. SFT $X=X_{\mathcal{F}}$ is a set of sequences specified by a directed graph $G$ with vertices in $\mathcal{A}$ and an edge from $a$ to $b$ iff $a b \notin \mathcal{F}$.


## Golden Mean Shift ((1, $\infty$ ) constraint): $\mathcal{F}=\{11\}$

- Adjacency matrix $A$ of $G$ is the square matrix indexed by $\mathcal{A}$ : $A_{a b}=\left\{\begin{array}{cc}1 & a b \notin \mathcal{F} \\ 0 & a b \in \mathcal{F}\end{array}\right\}$
- $h(X)=\log \lambda(A)$, where $\lambda(A)$ is the spectral radius of $A$.
- Characterization of entropies for $d=1$ (Lind):

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\left\{\log \lambda^{1 / q}\right\}
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where $\lambda$ is a Perron number and $q \in \mathbb{N}$

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## Examples of $\mathbb{Z}^{2}$ SFTs: hard square

- hard squares $\mathcal{A}=\{0,1\}, \mathcal{F}=\left\{11, \begin{array}{l}1 \\ 1\end{array}\right\}$
- $h($ hard square SFT $)=$ ???
- (Baxter) h( hard hexagons ) $=\log (\lambda)$ where $\lambda$ is an algebraic integer of degree 24.


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## Examples of $\mathbb{Z}^{2}$ SFTs: checkerboard (coloring) constraints

- $q$-checkerboard $\mathcal{C}_{q}: \mathcal{A}=\{1, \ldots, q\}, \mathcal{F}=\left\{\right.$ aa,, $\left.\begin{array}{l}a \\ a\end{array}\right\}$
- $h\left(C_{2}\right)=0$
- (Lieb): $h\left(C_{3}\right)=(3 / 2) \log (4 / 3)$
- $h\left(C_{4}\right)=$ ???


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- dimers:

- (Fisher-Kastelyn-Temperley):
$h($ Dimers $)=\frac{1}{16 \pi^{2}} \int_{-\pi}^{\pi} \int_{-\pi}^{\pi} \log (4+2 \cos \theta+2 \cos \phi) d \theta d \phi$
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| $L$ | $R$ | $T$ | $T$ | $T$ | $T$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $T$ | $T$ | $B$ | $B$ | $B$ | $B$ |
| $B$ | $B$ | $L$ | $R$ | $L$ | $R$ |
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## Topological entropy, $d \geq 2$

- Exact formula known only in a few cases.
- Characterization of entropies for $d \geq 2$ (Hochman-Meyerovitch):
\{right recursively enumerable (RRE) numbers $h \geq 0\}$
i.e, there is an algorithm that produces a sequence $r_{n} \geq h$
s.t. $r_{n} \rightarrow h$.

Proof:

- Necessity: Let $r_{n}:=\frac{\log \left|L_{n}\right|}{n^{d}}$ $r_{n} \rightarrow h$.
Since lim = inf, each $r_{n} \geq n$.
- Sufficiency (hard): Emulate Turing machine with an SFT.
- RRE's can be arbitrarily poorly computable, or even non-computable.


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- Necessity: Let $r_{n}:=\frac{\log \left|L_{n}\right|}{n^{d}}$. $r_{n} \rightarrow h$.
Since $\lim =\inf$, each $r_{n} \geq h$.
- Sufficiency (hard): Emulate Turing machine with an SFT.
- RRE's can be arbitrarily poorly computable, or even non-computable.


## Topological entropy, $d \geq 2$

- Exact formula known only in a few cases.
- Characterization of entropies for $d \geq 2$ (Hochman-Meyerovitch):
$\{$ right recursively enumerable (RRE) numbers $h \geq 0\}$
i.e, there is an algorithm that produces a sequence $r_{n} \geq h$
s.t. $r_{n} \rightarrow h$.

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## polynomial time approximation

- A polynomial time approximation algorithm: on input $n$, produces $r_{n}$ s.t. $\left|r_{n}-h\right|<1 / n$ and $r_{n}$ can be computed in time poly $(n)$.
- Theorem (Gamarnik-Katz, Pavlov): There is a polynomial time approximation algorithm to compute $h($ hard square SFT).


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## Measure-theoretic entropy

Given a shift-invariant Borel probability measure $\mu$ on $\mathcal{A}^{\mathbb{Z}^{d}}$,

- For finite $S \Subset \mathbb{Z}^{d}$,

- For finite disjoint $S, T$,

- Extend to finite $S$ and infinite $T$ :

$$
H_{\mu}(S \mid T):=\inf _{T^{\prime} \Subset T} H_{\mu}\left(S \mid T^{\prime}\right)
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## Entropy (entropy rate) of $\mu$

- $h(\mu):=\lim _{n \rightarrow \infty} \frac{H_{\mu}\left(B_{n}\right)}{n^{d}}$
- $d=1$ : Theorem: $h(\mu)=H_{\mu}(0 \mid\{-1,-2,-3, \ldots\})$
- $d=2$ : Let $\prec$ denotes lexicographic order: $(i, j) \prec\left(i^{\prime}, j^{\prime}\right)$ iff either $j<j^{\prime}$ or $\left(j=j^{\prime}\right.$ and $\left.i<i^{\prime}\right)$.
For $\bar{z} \in \mathbb{Z}^{2}$, let $\mathcal{P}(\bar{z}):=\left\{\bar{z}^{\prime} \in \mathbb{Z}^{2}: \bar{z}^{\prime} \prec \bar{z}\right\}$ the lexicographic past of $\bar{z}$, and $\mathcal{P}:=\mathcal{P}(0)$

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## Variational Principle for Topological Entropy

- For an SFT $X$,

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h(X)=\sup _{\mu} h(\mu)
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where the sup is taken over all shift-invariant Borel probability measures $\mu$ s.t. support $(\mu) \subseteq X$.

- Fact: The sup is always achieved. A measure which achieves the sup is called a measure of maximal entropy (MME).
- So for an MME $\mu, h(X)=h(\mu)=\int I_{\mu}(x) d \mu(x)$
- Under certain conditions, $h(X)=h(\mu)=\int I_{\mu}(x) d \nu(x)$ for some other invariant measures $\nu$
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## Rough Idea for showing $h(X)=I_{\mu}\left(s^{Z^{\delta}}\right)$

An MME $\mu$ should be "nearly uniform". So, $\mu$ captures entropy:


This is an average of $n^{d}$ terms of two types:

- Bulk terms: Terms that are far from the boundary of $B_{n}$
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Bulk terms are close to $I_{\mu}\left(s^{\mathbb{Z}^{d}}\right)$. All terms are uniformly

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## Rough Idea for showing $h(X)=I_{\mu}\left(s^{Z^{\sigma}}\right)$

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Example: $R_{3,4,3}$

Theorem: Let $X$ be a n.n. $\mathbb{Z}^{d}$ SFT and $\mu$ an MME on $X$. If (1) $X$ has a safe symbol $s$ - and -
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c & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\
\mid & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\
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| $c$ | $\cdot$ | $\cdot$ | $\cdot$ | $\cdot$ | $\cdot$ | $\cdot$ | $\cdot$ |
| $\mid$ | $\cdot$ | $\cdot$ | $\cdot$ | $\cdot$ | $\cdot$ | $\cdot$ | $\cdot$ |
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Moreover, if $d=2$ and convergence in hypothesis 2 is exponential, then there is a polynomial time algorithm to compute $h(X)$.
Proof of Moreover: Approximate $L$ by $\mu\left(s^{0} \mid S^{\partial R_{n, n, n}}\right)$.

- Accuracy is $e^{-\Omega(n)}$
- Claim: Computation time is $e^{O(n)}$
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## Proof of Claim, via transfer matrices

$$
\mu\left(s^{0} \mid s^{\partial R_{n, n, n}}\right)=\begin{array}{ccccccc} 
& S & S & S & S & S & \\
S & \cdot & \cdot & \cdot & \cdot & \cdot & S \\
\# & S & \cdot & \cdot & \cdot & \cdot & \cdot \\
S & S & S & S & \cdot & \cdot & S \\
& & & S & S & S & \\
& S & S & S & S & S & \\
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$M_{i}$ is transition matrix from column $i$ to column $i+1$ compatible with $s^{\partial R_{n, n, n}}$ and
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$$
\begin{aligned}
& S \quad S \quad S \quad S \\
& S \text {. . . . . S } \\
& \text { \# S . . . . . } S \\
& S \quad S \quad S \quad S \quad \cdot \quad S \\
& \mu\left(s^{0} \mid s^{\partial R_{n, n, n}}\right)=\frac{}{} \quad S \quad S \quad S \\
& S \text {. . . . } S \\
& \text { \# S • . . . . } S \\
& S \quad S \quad S \quad \cdot \quad \cdot \quad S \\
& S S S \\
& =\frac{\left(\prod_{i=-n}^{-1} M_{i}\right) \hat{M}_{0}\left(\prod_{i=1}^{n-1} M_{i}\right)}{\left(\prod_{i=-n}^{-1} M_{i}\right) M_{0}\left(\prod_{i=1}^{n-1} M_{i}\right)}
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## Extensions

- Weaken fixed point $s^{\mathbb{Z}^{d}}$ to periodic orbit
- Weaken safe symbol to topological strong spatial mixing
- Applies to
- hard squares
- monomer-dimers
- $q$-checkerboard SFT with $q \geq 6$
- Generalize results from entrony to pressure of $n n$. interactions on n.n. SFT's
- Applies to large sets of temperature regions for classical models in statistical physics, in both subcritical and supercritical regions:
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## End of talk

The following slides form a hodge-podge of topics that were not included in the talk.

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Theorem: Let $X$ be a $\mathbb{Z}^{d}$ n.n. SFT and $\mu$ an MME on $X$. If

- $X$ satisfies TSSM
(2) (for $d=2$ ) For some periodic orbit $O$ in $X$ and all $\omega \in O$

$$
L(\omega):=\lim _{a, b, c \rightarrow \infty} \mu\left(\omega(0) \mid \omega\left(\partial R_{a, b, c}\right)\right) \text { exists }
$$

Then


## Let $R_{a, b, c}:=[-a,-1] \times[1, c] \cup[0, b] \times[0, c]$

Example: $R_{3,4,3}$ :

$$
\begin{array}{ccccccccc}
\cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \\
\mid & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\
c & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\
\mid & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot & \cdot \\
& & & & \cdot & \cdot & \cdot & \cdot & \cdot \\
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Theorem: Let $X$ be a $\mathbb{Z}^{d}$ n.n. SFT and $\mu$ an MME on $X$. If (1) $X$ satisfies TSSM
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## Markov random fields

A Markov random field (MRF) is a shift-invariant Borel probability measure $\mu$ on $\mathcal{A}^{\mathbb{Z}^{d}}$ such that for any choice of:

- $T \Subset \mathbb{Z}^{d}$ s.t. $\partial S \subseteq T \subseteq \mathbb{Z}^{d} \backslash S$
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## Uniform MRF

Let $X$ be a n.n. SFT. For $S \Subset \mathbb{Z}^{d}$ and $y \in \mathcal{A}^{\partial S}$, let

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L_{S}^{y}(X):=\left\{x \in \mathcal{A}^{S}: x y \text { is legal }\right\}
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An MRF on $X$ is uniform if whenever $\mu(y)>0$, then for $x \in L_{S}^{y}(X)$


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Theorem (Lanford/Ruelle, Burton/Steif): Every MME on a n.n. SFT is a uniform MRF.

- Since $\mu$ is an MME, $\mu$ must be a uniform MRF.
- Since $s$ is a safe symbol,


## (1) For all $T \Subset \mathbb{Z}^{d}$ containing 0 ,



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## Decomposition

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\begin{gathered}
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\\
\bullet \bullet \quad \bullet \\
\bullet \\
\bullet \\
\bullet \\
\bullet \\
\bullet
\end{gathered} \cdot \cdot
$$

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& \begin{array}{llllll} 
& \bullet & \bullet & \bullet & \bullet & \\
\bullet & \cdot & \cdot & \cdot & \cdot & \bullet \\
\bullet & \cdot & \cdot & \cdot & \cdot & \bullet \\
\bullet & \cdot & \cdot & \cdot & \cdot & \bullet \\
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## Proof

- So,

$$
\log \mu\left(s^{B_{n}} \mid s^{\partial B_{n}}\right)=\sum_{\bar{z} \in B_{n}} \log \mu\left(s^{\bar{z}} \mid s^{\left.\partial R_{a(\bar{z}), b(\bar{z}), c(\bar{z})}\right)}\right.
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- By the convergence assumption, for "most" $\bar{z} \in B_{n}$

$$
\log \mu\left(s^{\bar{z}} \mid s^{\left.\partial R_{a(\bar{z}), b(\bar{z}), c(\bar{z})}\right) \approx \log 1}\right.
$$

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$$
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Thus, $h(X)=\lim _{n \rightarrow \infty} \frac{-\log \mu\left(s^{B_{n}} \mid s^{\partial B_{n}}\right)}{n^{d}}=-\log L . \square$

## Algorithmic consequence

Theorem: Let $X$ be a n.n. $\mathbb{Z}^{2}$ SFT and $\mu$ an MME on $X$. (1) $X$ has a safe symbol $s \quad-$ and -

and convergence is exponential
Then there is a polynomial time algorithm to compute $h(X)=-\log L$.

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## Strong Spatial Mixing

- An MRF $\mu$ satisfies strong spatial mixing (SSM) at rate $f(n)$
if for all $V \Subset Z^{d}, U \subset V$
all $u \in A^{U}$, and $v, v^{\prime} \in A^{\partial V}$ satisfying $\mu(v), \mu\left(v^{\prime}\right)>0$,
we have $\left|\mu(u \mid v)-\mu\left(u \mid v^{\prime}\right)\right| \leq|U| f\left(d\left(U, \Sigma_{\partial v}\left(v, v^{\prime}\right)\right)\right)$. where $\Sigma_{\partial v}\left(v, v^{\prime}\right)=\left\{t \in \partial V: v(t) \neq v\left(t^{\prime}\right)\right\}$
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if for all $V \Subset Z^{d}, U \subset V$
all $u \in A^{U}$, and $v, v^{\prime} \in A^{\partial V}$ satisfying $\mu(v), \mu\left(v^{\prime}\right)>0$,
we have $\left|\mu(u \mid v)-\mu\left(u \mid v^{\prime}\right)\right| \leq|U| f\left(d\left(U, \Sigma_{\partial v}\left(v, v^{\prime}\right)\right)\right)$. where $\Sigma_{\partial v}\left(v, v^{\prime}\right)=\left\{t \in \partial V: v(t) \neq v\left(t^{\prime}\right)\right\}$.



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## Stronger conclusion

Theorem (Briceno): Let $X$ be a $\mathbb{Z}^{d}$ n.n. SFT and $\mu$ an MME on $X$. If
(1) X satisfies TSSM
(2) $\mu$ satisfies SSM

Then for all invariant measures $\nu$ s.t. support $(\nu) \subseteq X$,

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h(X)=\int I_{\mu}(x) d \nu(x)
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## Applies to:

- hard sauares
- q-checkerboard with $q \geq 6$


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## Topological Pressure and Variational Principle

- Let $X$ be a shift space and $f: X \rightarrow \mathbb{R}$ a continuous function.
- Topological Pressure (defined by Variational Principle):

where the sup is taken over all shift-invariant Borel probability measures $\mu$ such that support $(\mu) \subseteq X$.
- Fact: The sup is always achieved.
- A measure which achieves the sup is called an equilibrium state.
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## Nearest-Neighbour interactions and Gibbs measures

- A nearest-neighbor interaction is a shift-invariant function $\Phi$ from a set of configurations on vertices and edges in $\mathbb{Z}^{d}$ to $\mathbb{R} \cup \infty$
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\mu(w \mid \delta)=\frac{e^{-U^{\Phi}(w \delta)}}{Z^{\Phi, \delta}(S)} .
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- $U^{\Phi}(w \delta)$ is the sum of all $\Phi$-values of $w \delta$ for vertices, edges
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## Examples of n.n. Gibbs measures

- uniform MME on n.n. SFT
- hard square model with activities
- ferromagnetic Ising model with no external field.


## Equilibrium states versus n.n. Gibbs measures

- Pressure of n.n. interaction $\Phi$ :

$$
P(\Phi):=\lim _{n \rightarrow \infty} \frac{\log Z^{\Phi}\left(B_{n}\right)}{n^{d}}
$$

where $Z^{\Phi}\left(B_{n}\right)$ is the "free boundary" normalization.

- Let $A_{\Phi}(x):=-\Phi(x(0))-\sum_{i=1}^{d} \Phi\left(x(0), x\left(e_{i}\right)\right)$.
- Fact: $P_{X_{\Phi}}\left(A_{\Phi}\right)=P(\Phi)$.
- Lanford-Ruelle Theorem: Every equilibrium state for $A_{\Phi}$ is a Gibbs measure for $\Phi$.
- Dobrushin Theorem: If $X_{\infty}$ is strongly irreducible, then every Gibbs measure for $\Phi$ is an equilibrium state for $A_{\Phi}$.
- These theorems hold in much greater generality.


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## Pressure representation and approximation

Theorem (Adams, Briceno, Marcus, Pavlov): Let $\mu$ a Gibbs measure for a n.n. interaction $\Phi$ with underlying $\mathbb{Z}^{d}$ n.n. SFT $X$. If

- $X$ satisfies TSSM
(2) For some periodic orbit $O$ in $X$ and all $\omega \in O$


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Moreover, if $d=2$ and convergence in hypothesis 2 is
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## D-condition

An SFT $X$ satisfies the $\mathbf{D}$-condition if

- there exist sequences of finite subsets $\left(\Lambda_{n}\right),\left(M_{n}\right)$ of $\mathbb{Z}^{d}$ such that $\Lambda_{n} \nearrow \infty, \Lambda_{n} \subseteq M_{n}, \frac{\left|M_{n}\right|}{\left|\Lambda_{n}\right|} \rightarrow 1$, such that
- for any alobally admissible $v \in \mathcal{A}^{\wedge_{n}}$ and finite $S \subset M_{n}^{c}$ and globally admissible $w \in \mathcal{A}^{S}$, we have that $v w$ is globally admissible.
Safe symbol $\Rightarrow$ TSSM $\Rightarrow$ D-condition


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## Connection with Thermodynamic Formalism

Theorem: Let $\mu$ a Gibbs measure for a n.n. interaction $\Phi$ with underlying $\mathbb{Z}^{d}$ n.n. SFT $X$. If

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## Connection with Thermodynamic Formalism

Theorem: Let $\mu$ a Gibbs measure for a n.n. interaction $\Phi$ with underlying $\mathbb{Z}^{d}$ n.n. SFT $X$. If

- $X$ satisfies the D-condition
- $I_{\mu}=A_{\psi}$ for some absolutely summable interaction $\psi$ s.t. $X_{\psi}=X$,
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- Assuming adjacency matrix $A$ is irreducible and aperiodic, there is a unique $\mathrm{MME} \mu_{\max }$,

where $\lambda=\lambda(A)$ and $r$ is a right eigenvector for $\lambda$, and stationary vector $r_{i} \ell_{i}$ where $\ell$ is a left eigenvector for $\lambda$ (suitably normalized)
- Thus, if $\mu\left(w_{1} w_{2} \ldots w_{n-1} w_{n}\right)>0$, then

- Thus, fixing $w_{1}, w_{n}$,
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## Entropy representation for MME, $d=1$

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\begin{aligned}
I_{\mu}(x) & =-\log \mu(x(0) \mid x(\mathcal{P})) \\
& =-\log P_{x_{0} x-1} \\
& =\log \lambda+\log r_{x_{-1}}-\log r_{x_{0}}
\end{aligned}
$$

- So, for all invariant measures $\nu$,


In particular, if the SFT has a fixed point $x^{*}:=a^{\mathbb{Z}}$ and $\nu$ is the delta measure on $x^{*}$, then on

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h(X)=\int I_{\mu}(x) d \nu(x)=I_{\mu}\left(x^{*}\right)=-\log \mu\left(x^{*}\right)
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and so $h(X)$ can be computed from the value of the
information function at only one point.

- In this case, $I_{\mu}(x)$ is defined everywhere.


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[^0]:    Examples: Yes: Hard squares $(s=0)$
    No: Checkerboard shifts, Dimers, Monomer-dimers

