

# A dispersive regularization for modified Camassa-Holm equation

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# The modified Camassa-Holm (mCH) equation

The mCH equation

$$m_t + [(u^2 - u_x^2)m]_x = 0, \quad m = u - u_{xx}, \quad x \in \mathbb{R}, \quad t > 0.$$

(Fokas, 1995; Olver & Rosenau, 1996; Qiao, 2006)

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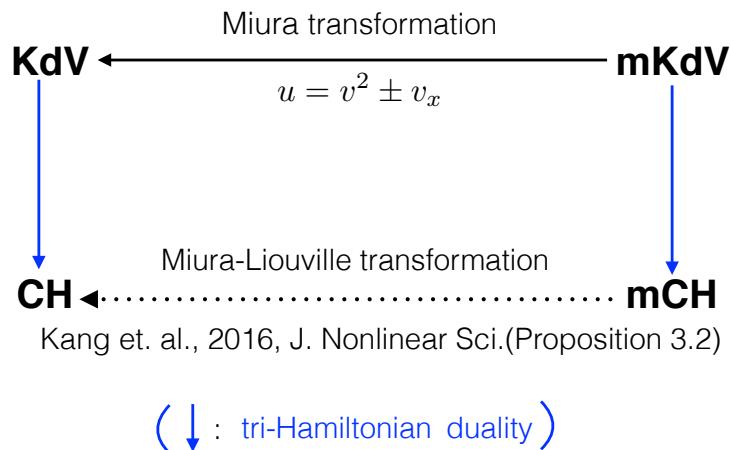


Figure 1: Relations with KdV, mKdV and CH equations

# Local solutions

For the mCH equation:

- ▶ local existence and uniqueness of strong solutions:

Fu, Gui, Liu, Qu, 2013, JDE (Besov space)

Gui, Liu, Olver, Qu, 2013, CMP ( $H^s(\mathbb{R})$ ,  $s > 1/2$ )

Himonas, Mantzavinos, 2014, J. Nonlinear Sci. (Hölder space)

...

- ▶ finite time blow-up behaviors:

Gui, Liu, Olver, Qu, 2013, CMP

Liu, Olver, Qu, 2014, Anal. Appl.

Chen, Liu, Qu, Zhang 2015, Adv. Math.

...

**Question:** How to extend weak solutions globally?

# Definition of weak solutions

mCH equation is equivalent to

$$\begin{aligned} & (1 - \partial_{xx})u_t + [(u^2 - u_x^2)(u - u_{xx})]_x \\ &= (1 - \partial_{xx})u_t + (u^3 + uu_x^2)_x - \frac{1}{3}(u^3)_{xxx} + \frac{1}{3}(u_x^3)_{xx} = 0. \end{aligned}$$

Multiply the equation by a test function  $\phi \in C_c^\infty(\mathbb{R} \times [0, \infty))$  and integrate by parts:

$$\begin{aligned} \mathcal{L}(u, \phi) &= \int_0^\infty \int_{\mathbb{R}} u(x, t)[\phi_t(x, t) - \phi_{txx}(x, t)] dx dt \\ &\quad - \frac{1}{3} \int_0^\infty \int_{\mathbb{R}} u_x^3(x, t)\phi_{xx}(x, t) dx dt - \frac{1}{3} \int_0^\infty \int_{\mathbb{R}} u^3(x, t)\phi_{xxx}(x, t) dx dt \\ &\quad + \int_0^\infty \int_{\mathbb{R}} (u^3 + uu_x^2)\phi_x(x, t) dx dt = - \int_{\mathbb{R}} \phi(x, 0)m_0(x) dx. \end{aligned}$$

# Properties of $G$ and $G'$

Fundamental solution of Helmholtz operator  $1 - \partial_{xx}$ : ( $m = u - u_{xx}$ )

$$G(x) = \frac{1}{2}e^{-|x|} \quad \Rightarrow \quad u = G * m.$$

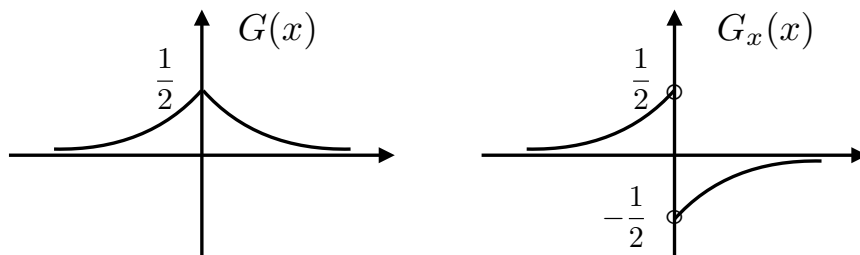


Figure 2:  $G$  and  $G'$ .

- ▶  $G - G_{xx} = \delta$ ;  $V(G) = 1$ ,  $V(G') = 2$ .
- ▶  $\|G\|_{L^\infty} = \frac{1}{2}$ ,  $\|G'\|_{L^\infty} = \frac{1}{2}$ ;  $\|G\|_{L^1} = 1$ ,  $\|G'\|_{L^1} = 1$ ;

# $N$ -peakon weak solutions

$N$ -peakon weak solutions:

$$u^N(x, t) = \sum_{i=1}^N p_i(t)G(x - x_i(t)), \quad m^N = \sum_{i=1}^N p_i(t)\delta(x - x_i(t)).$$

When  $x_1(t) < x_2(t) < \dots < x_N(t)$ , one has (Gui et.al. 2013):

$$\begin{cases} \frac{d}{dt}p_i = 0, \\ \frac{d}{dt}x_i = \frac{1}{6}p_i^2 + \frac{1}{2} \sum_{j<i} p_i p_j e^{x_j - x_i} + \frac{1}{2} \sum_{j>i} p_i p_j e^{x_i - x_j} + \sum_{1 \leq m < i < n \leq N} p_m p_n e^{x_m - x_n}. \end{cases}$$

$N = 1$ : solitary wave solutions (one peakon):

$$u(x, t) = pG(x - x(t)), \quad x'(t) = \frac{p^2}{6}.$$



# Finite time collision

Consider initial data

$$m_0 = p_1 \delta(x - c_1) + p_2 \delta(x - c_2), \quad c_1 < c_2, \quad p_1^2 > p_2^2.$$

The two peakons ODE:

$$\begin{cases} \frac{d}{dt} x_1(t) = \frac{1}{6} p_1^2 + \frac{1}{2} p_1 p_2 e^{x_1(t) - x_2(t)}, \\ \frac{d}{dt} x_2(t) = \frac{1}{6} p_2^2 + \frac{1}{2} p_1 p_2 e^{x_1(t) - x_2(t)}. \end{cases}$$

$\implies$

$$\frac{d}{dt} (x_1 - x_2) = \frac{1}{6} (p_1^2 - p_2^2) > 0.$$

This two peakons will collide with each other at

$$t^* := \frac{6(c_2 - c_1)}{p_1^2 - p_2^2}.$$

Global trajectories  $\not\Rightarrow$  global peakon solutions

# Finite time collide between peakons

**Question:** How to extend trajectories globally and obtain global  $N$ -peakon weak solutions?

# Problem: non-Lipschitz vector field

Characteristic equation for mCH:

$$\frac{d}{dt}x(t) = u^2(x(t), t) - u_x^2(x(t), t).$$

Consider  $u^N(x, t) = \sum_{i=1}^N p_i G(x - x_i(t))$ :

$$\frac{d}{dt}x_i(t) = [u^N(x_i(t), t)]^2 - [u_x^N(x_i(t), t)]^2, \quad i = 1, \dots, N.$$

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Jump discontinuous, non-Lipschitz vector field.

How about mollify the vector field one time?  
(Vortex blob method for 2D Euler equation)

# Speed for one peakon $u(x, t) = pG(x - x(t))$

**Fact:**  $x'(t) = \frac{p^2}{6}$ .

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From characteristics equation:  $x'(t) = (u^2 - u_x^2)(x(t), t)$ :

$$\begin{aligned}x'(t) &= p^2 G^2(x(t) - x(t)) - p^2 G_x^2(x(t) - x(t)) \\ &= p^2 G^2(0) - p^2 G_x^2(0) = \frac{p^2}{6}.\end{aligned}$$

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$\Rightarrow$  the **correct** definition for  $G_x^2(0)$ :

$$G_x^2(0) = G^2(0) - \frac{1}{6} = \frac{1}{12}.$$

# One peakon: one time mollification

Let  $\rho(x)$  be an even function with  $\int \rho dx = 1$ ,  $\varepsilon > 0$ .

$$\rho_\varepsilon(x) = \frac{1}{\varepsilon} \rho\left(\frac{x}{\varepsilon}\right), \quad G^\varepsilon(x) = (\rho_\varepsilon * G)(x).$$

Then, one time mollification gives wrong travelling speed:

$$(\rho_\varepsilon * G_x)^2(0) \rightarrow 0, \quad [\rho_\varepsilon * (G_x^2)](0) \rightarrow \frac{1}{4}, \quad \varepsilon \rightarrow 0.$$



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Double mollification gives the right one (independent of  $\rho$ )

$$\lim_{\varepsilon \rightarrow 0} [\rho_\varepsilon * (G_x^\varepsilon)^2](0) = \frac{1}{12}. \quad (*)$$

# Double mollification

For  $N$ -peakon:

$$u^{N,\epsilon}(x; \{x_k\}) := \sum_{i=1}^N p_i G^\epsilon(x - x_i), \quad U_\epsilon^N(x; \{x_k\}) := [u^{N,\epsilon}]^2 - [u_x^{N,\epsilon}]^2.$$

Double mollification (particle blob method):

$$\frac{d}{dt} x_i^\epsilon(t) = (\rho_\epsilon * U_\epsilon^N)(x_i^\epsilon(t); \{x_k^\epsilon(t)\}), \quad i = 1, \dots, N.$$

$\Rightarrow$  Global approximated trajectories:

$$x_i^\epsilon(t) : t \in [0, \infty), \quad i = 1, 2, \dots, N.$$

# Collision avoidance

Initial data  $x_i^\epsilon(0) = c_i$ :

$$m_0^N = \sum_{i=1}^N p_i \delta(x - c_i), \quad c_1 < c_2 < \cdots < c_N, \quad \sum_{i=1}^N |p_i| \leq M_0.$$

**Theorem (Theorem 3.2, Gao, Li & Liu 2018)**

*Let  $\{x_i^\epsilon(t)\}_{i=1}^N$  be trajectories obtained by approximated ODEs with initial data  $x_i^\epsilon(0) = c_i$ . Then, for any  $t > 0$ , we have*

$$x_1^\epsilon(t) < x_2^\epsilon(t) < \cdots < x_N^\epsilon(t), \quad \forall t > 0.$$

**Proof:** only need the following estimate:

$$-C_\epsilon(x_{k+1}^\epsilon - x_k^\epsilon) \leq \frac{d}{dt}(x_{k+1}^\epsilon - x_k^\epsilon) \leq C_\epsilon(x_{k+1}^\epsilon - x_k^\epsilon).$$

# Weak consistence

Approximated  $N$ -peakon solutions:

$$u^{N,\epsilon}(x, t) = \sum_{i=1}^N p_i G^\epsilon(x - x_i^\epsilon(t)).$$

“Distance” to weak solutions:

$$E_{N,\epsilon} = \mathcal{L}(u^{N,\epsilon}, \phi) + \int_{\mathbb{R}} \phi(x, 0) m_0^N(dx).$$

We have

Proposition (Proposition 3.1, Gao, Li & Liu 2018)

*There exists a constant  $C$  independent of  $N, \epsilon$  such that  $E_{N,\epsilon}$  satisfies*

$$|E_{N,\epsilon}| \leq C\epsilon.$$

# Limiting trajectories

Trajectories  $x_i^\epsilon(t)$  are globally Lipschitz:

$$\left| \frac{d}{dt} x_i^\epsilon(t) \right| \leq \frac{1}{2} M_0^2.$$

$\Rightarrow \{x_i^\epsilon(t)\}_{\epsilon>0}$  is uniformly bounded and equicontinuous in  $[0, T]$ .

Arzelà-Ascoli Theorem  $\Rightarrow \{x_i(t)\}_{i=1}^N \subset C([0, +\infty))$  satisfying

$$\left| \frac{d}{dt} x_i(t) \right| \leq \frac{1}{2} M_0^2, \quad i = 1, \dots, N$$

$x_i(t)$  never cross with each other.

# Global $N$ -peakon weak solutions

Approximated  $N$ -peakon weak solutions:

$$u^{N,\epsilon}(x, t) = \sum_{i=1}^N p_i G^\epsilon(x - x_i^\epsilon(t))$$

converges a.e.  $(x, t)$  to

$$u^N(x, t) = \sum_{i=1}^N p_i G(x - x_i(t)).$$

Lebesgue dominated convergence theorem implies

$$u^{N,\epsilon} \rightarrow u^N, \quad u_x^{N,\epsilon} \rightarrow u_x^N, \quad \epsilon \rightarrow 0, \quad L_{loc}^1(\mathbb{R} \times [0, +\infty))$$

+ weak consistency  $\Rightarrow$

$u^N(x, t)$  is an  $N$ -peakon weak solution to the mCH equation.

# Global existence of weak solutions in $\mathcal{M}(\mathbb{R})$

Theorem (Theorem 4.1, Gao, Li & Liu 2018)

*For any initial Radon measure  $m_0 \in \mathcal{M}(\mathbb{R})$ , there is a global weak solution  $u$  to the  $mCH$  equation, which satisfies that*

$$u \in C([0, \infty); H^1(\mathbb{R})) \cap L^\infty(0, \infty; W^{1, \infty}(\mathbb{R})) \cap W^{1, \infty}(0, \infty; L^\infty(\mathbb{R})),$$

*and for any  $T > 0$ ,*

$$u, \quad u_x \in BV(\mathbb{R} \times [0, T)).$$

*Moreover, we have*

$$m = (1 - \partial_{xx})u \in \mathcal{M}(\mathbb{R} \times [0, T))$$

*and there exists a subsequence of  $m^N$  (also labeled as  $m^N$ ) such that*

$$m^N \xrightarrow{*} m \text{ in } \mathcal{M}(\mathbb{R} \times [0, T)) \quad (\text{as } N \rightarrow \infty).$$

# Equations with multi-peakon solutions

$f$  $g$ -family of equations for multi-peakon solutions (Anco & Recio 2019):

$$m_t + f(u, u_x)m + [g(u, u_x)m]_x = 0, \quad x \in \mathbb{R}, \quad t > 0.$$

- (i)  $f = u_x, g = u$ : CH equation;
- (ii)  $f = 0, g = (u^2 - u_x^2)^n$  ( $n \in \mathbb{N}_+$ ): generalized modified Camassa-Holm (gmCH) equation.

$$m_t + [(u^2 - u_x^2)^n m]_x = 0, \quad m = u - u_{xx}, \quad x \in \mathbb{R}, \quad t > 0.$$

$n = 1$ : modified Camassa-Holm equation.



# Double mollification for the gmCH

The gmCH equation ( $n \in \mathbb{Z}_+$ ):

$$m_t + [(u^2 - u_x^2)^n m]_x = 0, \quad m = u - u_{xx}, \quad x \in \mathbb{R}, \quad t > 0.$$

Double mollification:

$$u^{N,\epsilon}(x; \{x_k\}_{k=1}^N) := \sum_{k=1}^N p_k G^\epsilon(x - x_k),$$

$$U_\epsilon^N(x; \{x_k\}_{k=1}^N) := [(u^{N,\epsilon})^2 - (\partial_x u^{N,\epsilon})^2]^n(x; \{x_k\}_{k=1}^N),$$

and

$$U^{N,\epsilon}(x; \{x_k\}_{k=1}^N) := (\rho_\epsilon * U_\epsilon^N)(x; \{x_k\}_{k=1}^N).$$

The regularized ODEs:

$$\frac{d}{dt} x_i^\epsilon(t) = U^{N,\epsilon}(x_i^\epsilon(t); \{x_k^\epsilon(t)\}_{k=1}^N), \quad i = 1, \dots, N,$$

# Traveling speed of single peakon solutions:

Consider the case for single peakon weak solutions. When  $N = 1$ ,

$$\frac{d}{dt}x^\varepsilon(t) = U^{1,\varepsilon}(x^\varepsilon(t), t) = p^{2n} (\rho_\varepsilon * [(G^\varepsilon)^2 - (G_x^\varepsilon)^2]^n)(0).$$

We have the following theorem:

**Theorem (Theorem 3.2, Y. Gao & H. Liu 2021)**

*The following identity holds*

$$\lim_{\varepsilon \rightarrow 0} (\rho_\varepsilon * [(G^\varepsilon)^2 - (G_x^\varepsilon)^2]^n)(0) = \frac{1}{2^{2n}} \sum_{k=0}^n \binom{n}{k} \frac{(-1)^k}{2k+1}.$$

*For any amplitude  $p \neq 0$  and  $n \in \mathbb{N}$ , the single peakon weak solutions to the gmCH equation is given by*

$$u(x, t) = pG(x - c_n t), \quad c_n = \left(\frac{p}{2}\right)^{2n} \sum_{k=0}^n \binom{n}{k} \frac{(-1)^k}{2k+1}.$$

*Thank you!*